

# Evaluation of a Novel Optical Trapezoid Model for Estimation of Large-Scale Root Zone Soil Moisture Based on MODIS Satellite Observations and Reference Cosmic-Ray Measurements



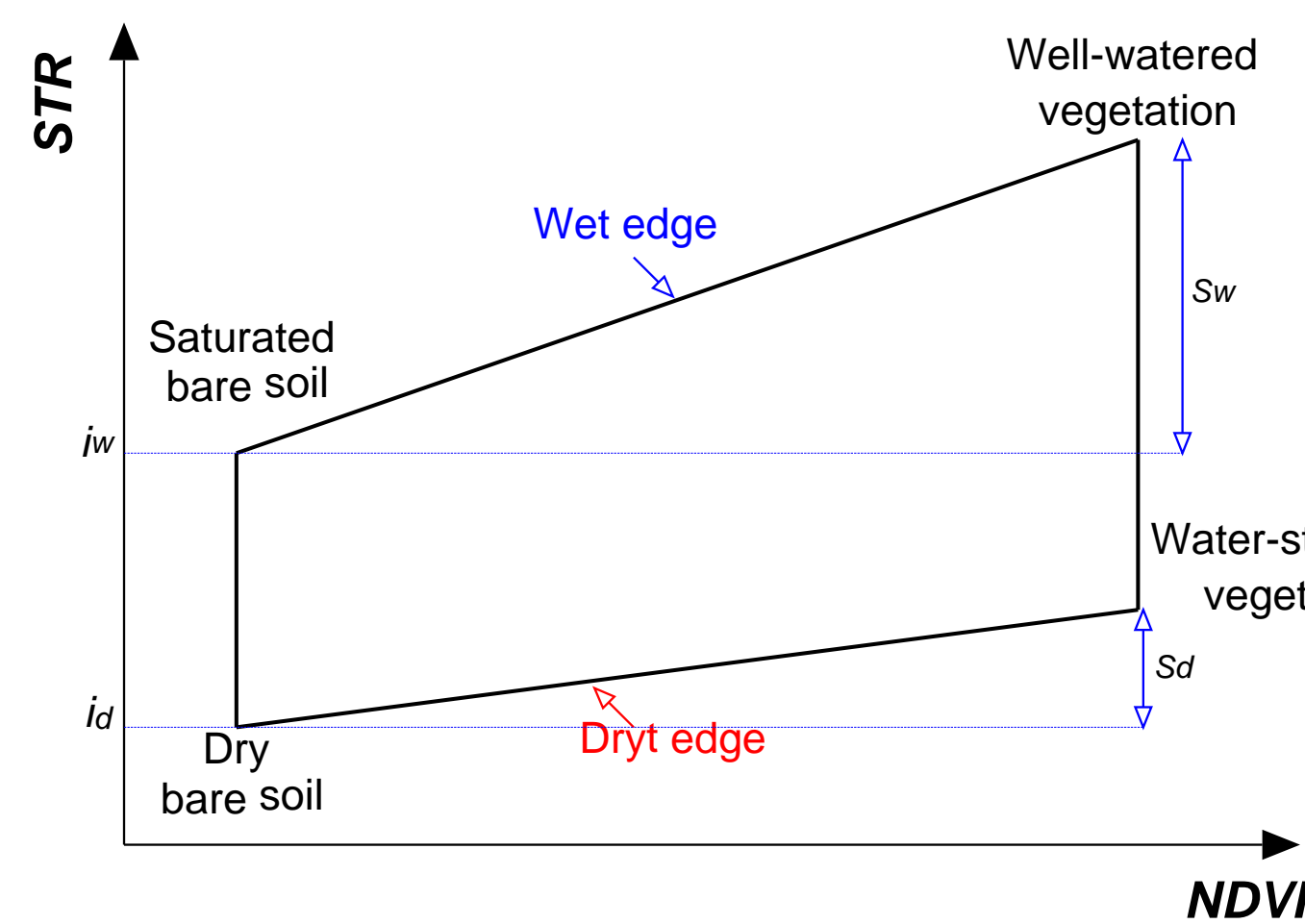
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## Background

- Recently, *Sadeghi et al. (2017)* proposed a physical “optical trapezoid model” (OPTRAM) for remote sensing of soil moisture (SM).
- OPTRAM is based on the pixel distribution within the shortwave infrared transformed reflectance (STR)-normalized difference vegetation index (NDVI) space, defined as:

$$W = \frac{\theta}{\theta_s} = \frac{i_d + s_d NDVI - STR}{i_d - i_w + (s_d - s_w) NDVI}$$

$$\begin{cases} STR_d = i_d + s_d NDVI \\ STR_w = i_w + s_w NDVI \\ W = \frac{STR - STR_d}{STR_w - STR_d} \end{cases}$$



- The advantage of the STR- $\theta$  space over the conventional triangle/trapezoid approach (LST- $\theta$  space) (*Carlson et al., 1994*) is that: (1) it only requires optical data; and (2) it can be universally parameterized for a given location because STR- $\theta$  is not affected by ambient atmospheric factors.
- However, the STR- $\theta$  space is sensitive to oversaturated pixels (due to ponding water) and hence occasionally yields  $W > 1$  (*Sadeghi et al., 2017*).
- To solve this issue and to obtain a robust model parameterization, we used long-term MODIS data and evaluated OPRAM across regions with various climates, land-covers, and soil types for estimation of SM.
- Cosmic-ray neutron probe (CRNP) observations as well as satellite soil moisture products including SMAP, SMOS, and ASCAT were used to evaluate OPRAM's accuracy. CRNPs exhibit a volume of influence similar to the size of a MODIS pixel.

## Methodology

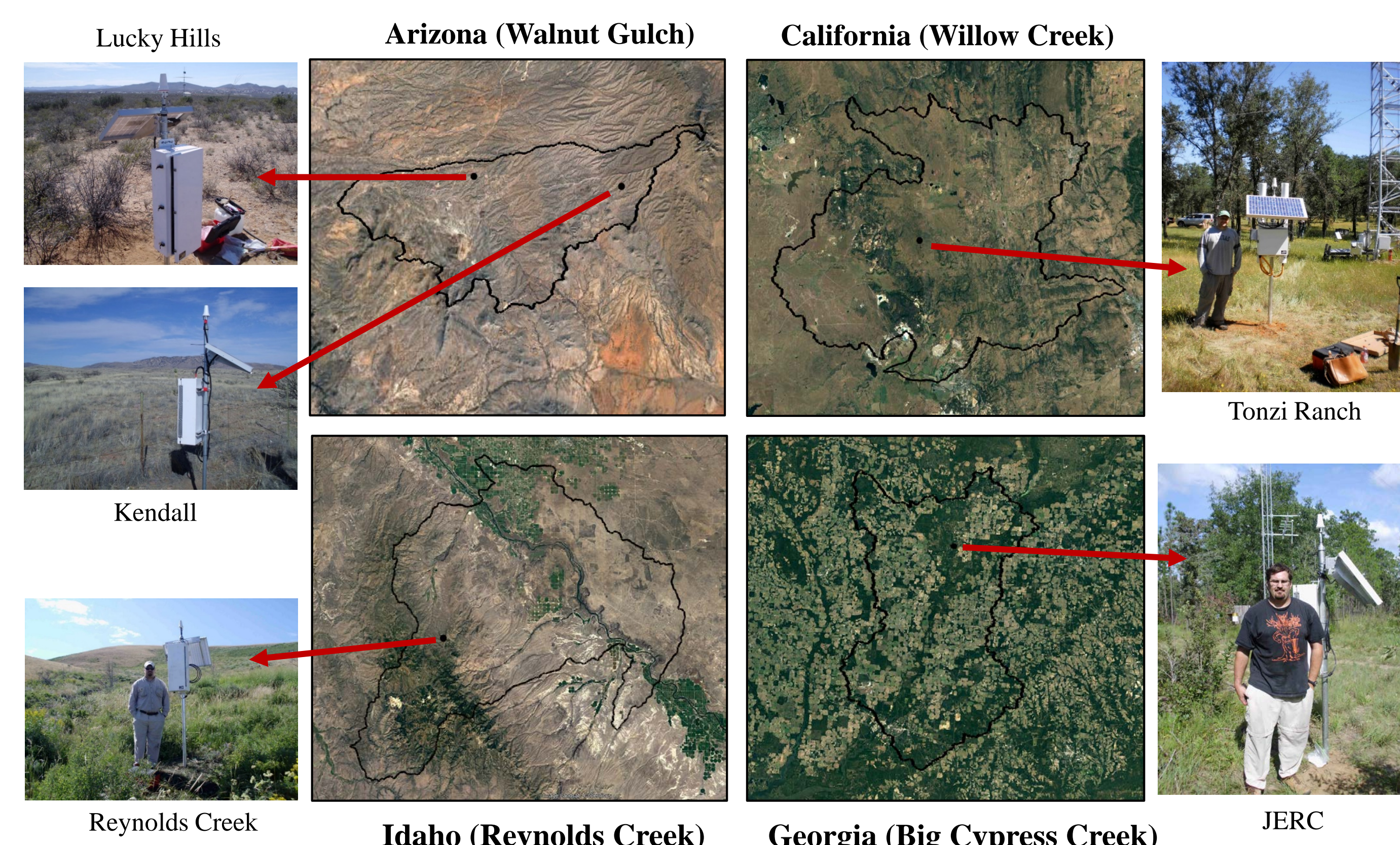
### Test Regions

- 4 Watersheds in the U.S. with different climates, land covers, soil types were selected.

### Ground-based soil moisture

- Cosmic-ray neutron probe observations (CRNP)** were collected from the Lucky Hills and Kendal sites (Arizona), Tonzi Ranch (California), Reynolds Creek (Idaho), and JERC (Georgia) from 2011 to 2017.
- The *Franz et al. (2013)* framework was used to correct soil moisture ( $\theta_v$ ) for all hydrogen sources, i.e., lattice water ( $\theta_w$ ), atmospheric water vapor, and soil organic matter water ( $\theta_{soeq}$ ).

$$\theta_v = \left[ \begin{array}{c} 0.0808 \\ \left( \frac{N_{pnh}}{N_0} \right) - 0.372 \end{array} \right] - 0.115 - \theta_w - \theta_{soeq} \rho_b$$



## Methodology - Continued

### Satellite data

- MODIS:** Long-term land surface reflectance products (MOD09A1, 500m, 8-day) from 2001 to 2017 were used. Bands 1 (Red), 2 (NIR) and 7 (SWIR) were utilized to define STR-NDVI space.
- SMAP** level-3 surface soil moisture product (L3\_SM\_P, descending 6:00 a.m.; 36 km; daily)
- ASCAT** soil moisture product (EUMETSAT H109, H110; 12.5 km; daily)
- SMOS** level-3 soil moisture product (Version 3.0, 6:00 a.m.; 25 km, daily)

### Bias reduction and CDF Matching

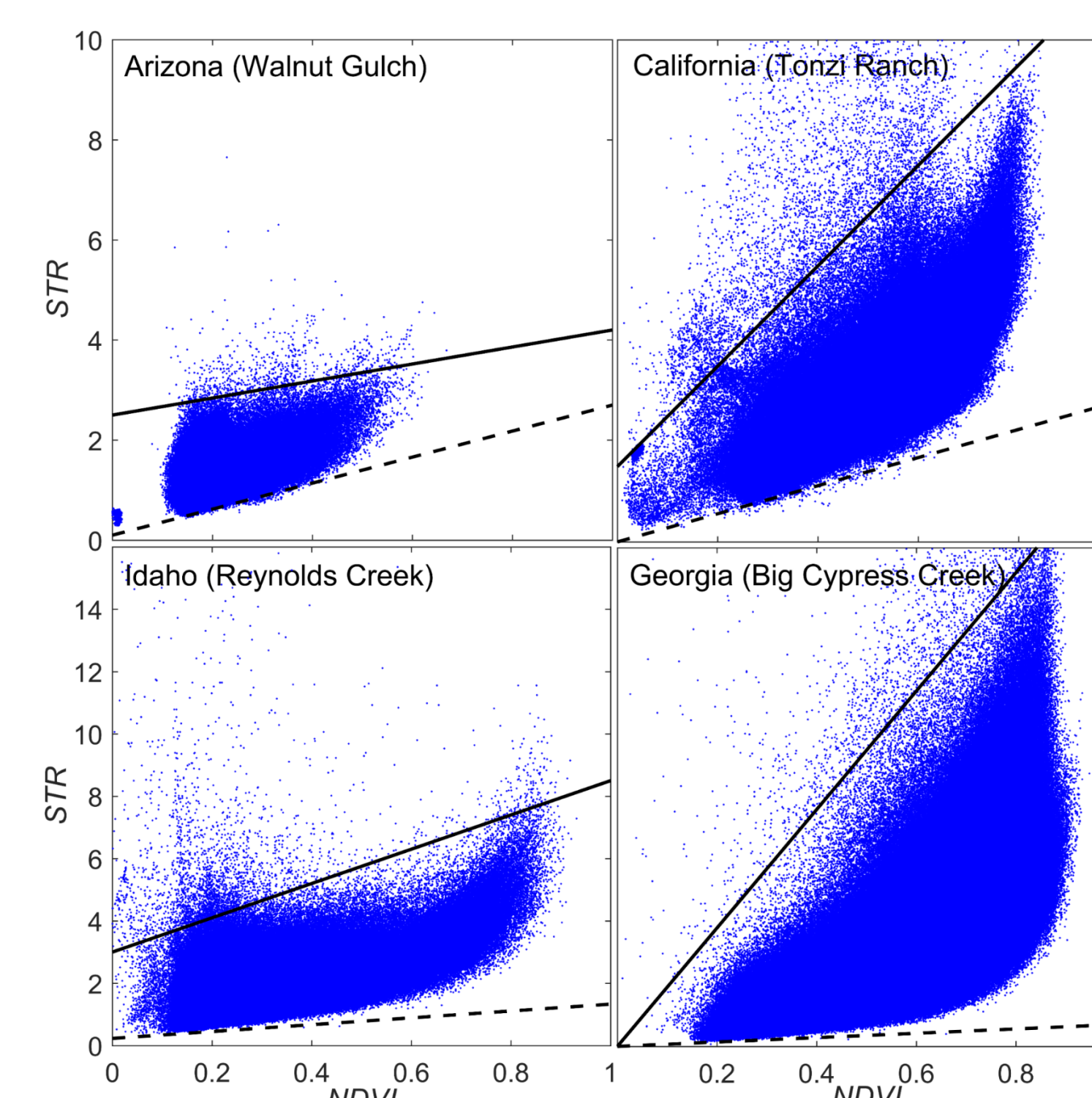
- The Cumulative Distribution Function (CDF) matching method has been recommended for reducing systematic biases between two datasets, e.g., satellite-based estimates and in situ measurements.
- A simple strategy (*Reichle and Koster, 2004*) was applied to match the CDF of estimated soil moisture to that of the in situ CRNP observations based on a transformation to consistent normal deviates

$$CDF_{ground}(x') = CDF_{satellite}(x)$$

## Results

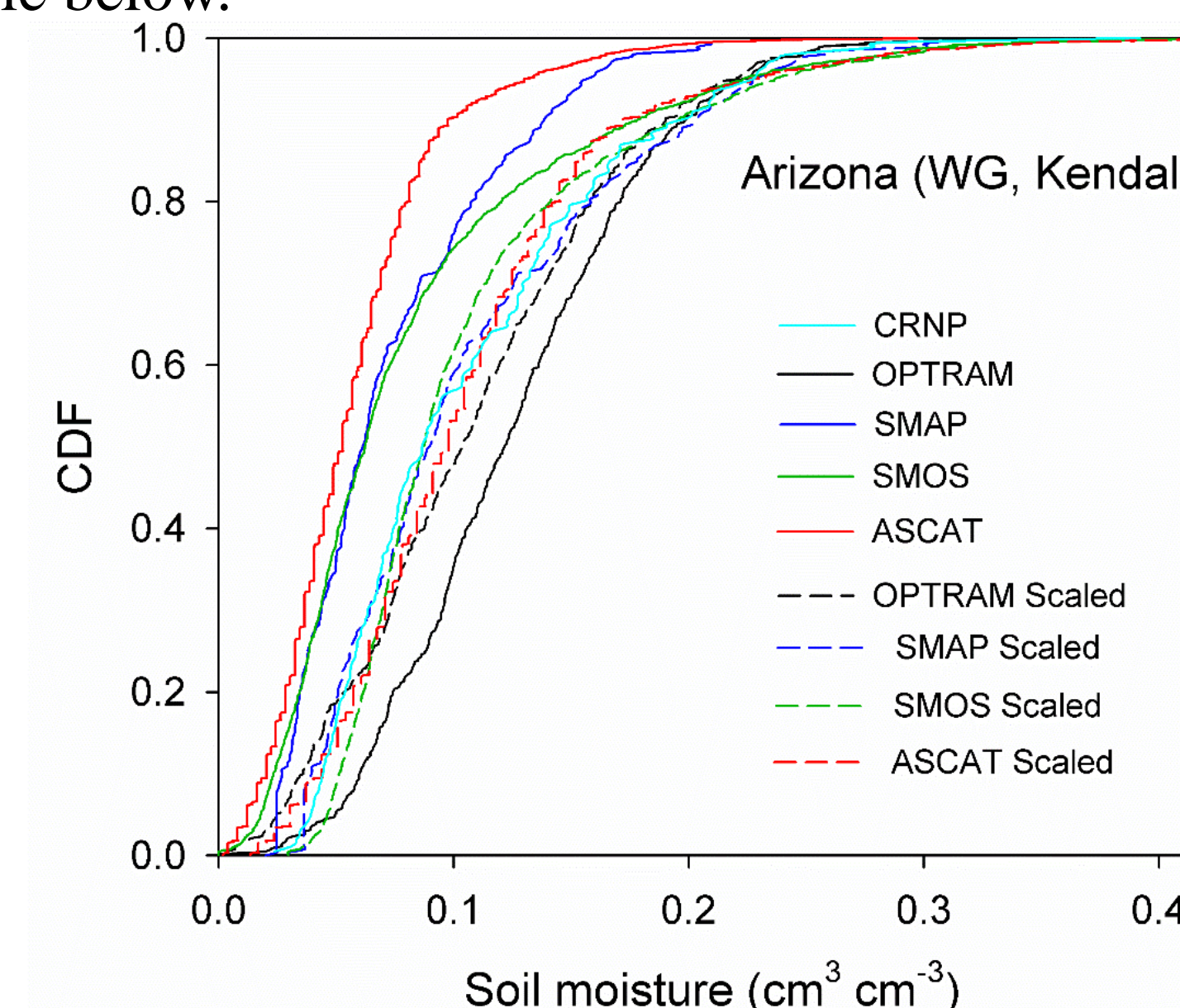
### Model Parametrization

- A nearly trapezoidal shape is formed for all four watersheds.
- A universal parametrization with long-term MODIS data was performed to derive dry and wet edge parameters. The figure below depicts the obtained STR- $\theta$  spaces and optimized edges.



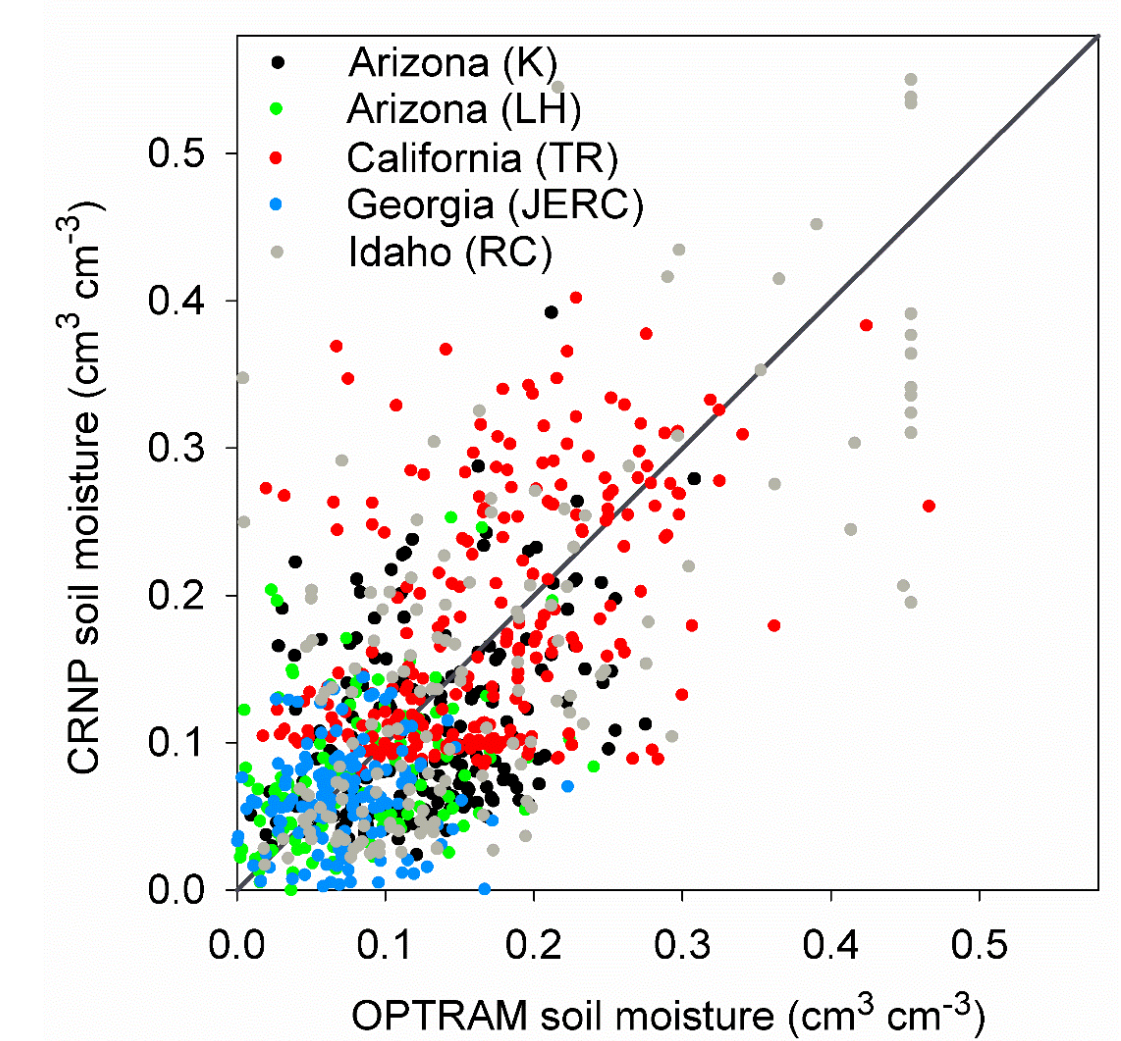
### CDF Matching

- CDFs based on CRNPs and the original and rescaled soil moisture estimates from OPRAM, SMAP, SMOS, and ASCAT for Kendal CRNP site (AZ) are depicted as an example below.



## Results - Continued

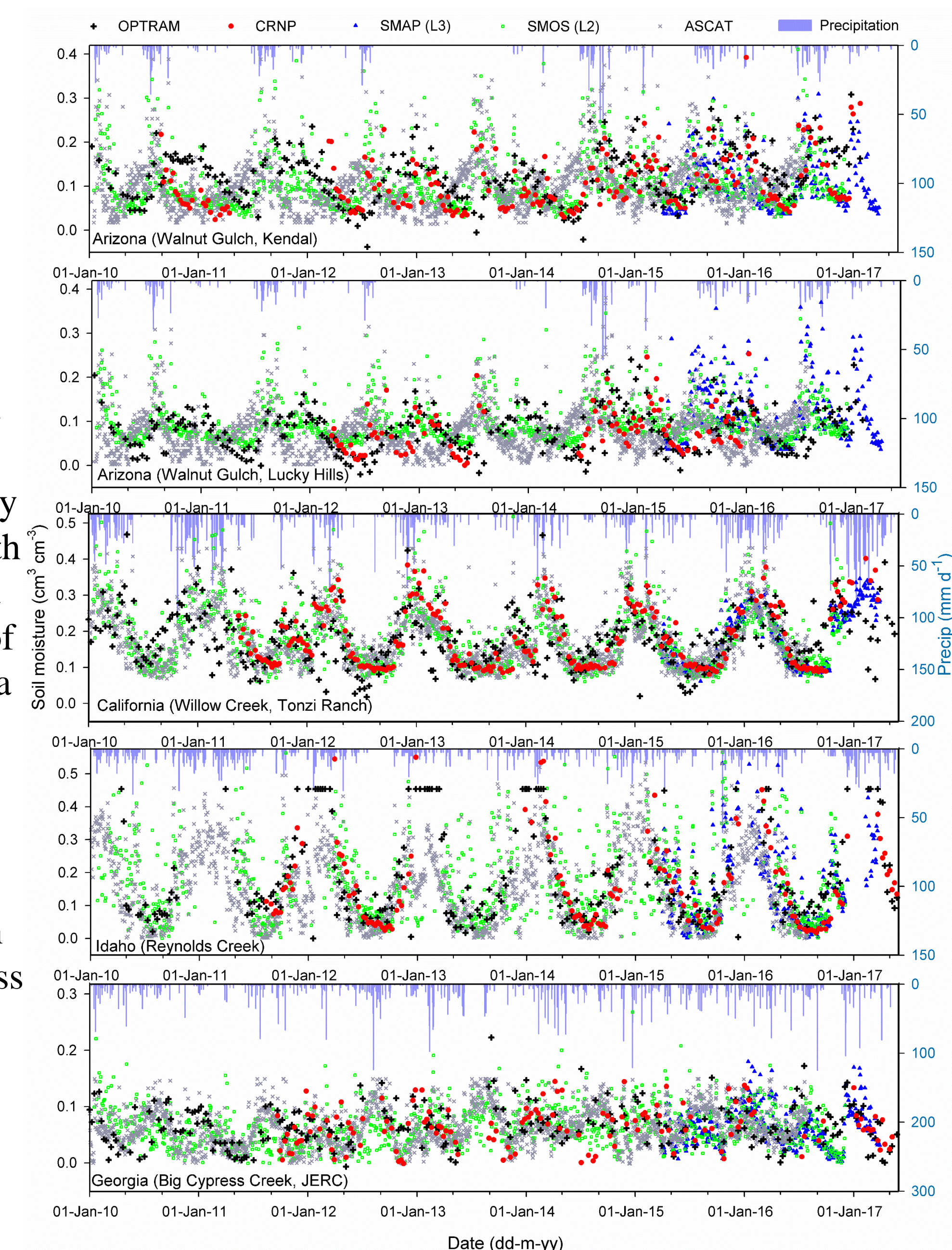
- Scatterplots comparing rescaled estimated soil moisture (OPTRAM) and CRNP based measurements for the five selected sites indicate a good performance of OPRAM.
- The accuracy of OPRAM was different for the four selected sites with a mean RMSE 0.07 cm³ cm⁻³ (see the Table), which is reasonable for the optical domain and the large number of analyzed MODIS images.



Metrics	Arizona (Lucky Hills)	Arizona (Kendal)	California (Tonzi Ranch)	Idaho (Reynolds Creek)	Georgia (JERC)
<b>R</b>	0.32	0.36	0.46	0.70	0.10
<b>RMSE</b>	0.065	0.072	0.085	0.083	0.050
<b>Bias</b>	-0.015	-0.036	0.012	0.011	-0.007
<b>ubRMSE</b>	0.0638	0.0624	0.0848	0.0822	0.0501

- OPTRAM yields SM dynamics similar to those of CRNPs and microwave satellites during 2015 to 2017.

- Like microwave satellites, OPRAM responds to SM dynamics as well as precipitation events quite well.



- Although CRNPs measure the effective SM within a wide range, the discrepancy between sensing depth of optical signals and measurement depth of cosmic-ray could be a source of error.

- Another source of error could be high biomass, which leads to high uncertainty in CRNP data. A biomass correction would be required, especially for the JERC site in Georgia.

## Conclusion

- The obtained results indicate reasonable accuracy of OPRAM across regions with different climates, land covers, and soil types for large-scale estimation of soil moisture.
- OPTRAM yields similar SM trends as SMAP, SMOS, and ASCAT soil moisture products.
- CRNP observations could be an option to fill the scale gap between point measurements and satellite-based estimations of soil moisture.

## Reference

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The authors gratefully acknowledge support from the National Science Foundation (NSF) under grant No. 1521469.

